THE MAGNETIC INDUCTION OF THE SYSTEM CONSISTING
OF A COIL AND A FERROMAGNETIC
SPHERICAL BODY

By

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The magnetic induction is calculated for two configurations of a ferromagnetic spherical body surrounded by a current-carrying conductor. The first case is for an infinitesimally thin current band carrying a stationary current and surrounding a spherical shell. The second case is for a current band of finite width carrying a stationary current and surrounding a solid sphere. The ferromagnetic bodies are assumed to be linear and...
Item 20 (Cont)

homogeneous. The reduction of the solution for the dipole term to that of a filamentary circular current-carrying conductor is shown in the first case when the permeability of the ferromagnetic spherical shell is allowed to approach that of free space.
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LIST OF ABBREVIATIONS

- **A**: Vector potential function
- **$A_{\psi}$**: Azimuthal ($\psi$) component of $\vec{A}$
- **$A_{\psi I}$**: Azimuthal component of $\vec{A}$ in region I
- **$A_{\psi II}$**: Azimuthal component of $\vec{A}$ in region II
- **$A_{\psi III}$**: Azimuthal component of $\vec{A}$ in region III
- **$A_{\psi IV}$**: Azimuthal component of $\vec{A}$ in region IV
- **$\vec{B}$**: Magnetic flux density or magnetic induction
- **$B_1$**: Magnetic flux density in medium I
- **$B_2$**: Magnetic flux density in medium II
- **$B_r$**: Radial component of the magnetic flux density
- **$B_\theta$**: Theta component of the magnetic flux density
- **$B_{r I}$**: Radial component of $\vec{B}$ in region I
- **$B_{r II}$**: Radial component of $\vec{B}$ in region II
- **$B_{r III}$**: Radial component of $\vec{B}$ in region III
- **$B_{r IV}$**: Radial component of $\vec{B}$ in region IV
- **$B_{n 1}$**: Normal component of $\vec{B}$ in medium 1
- **$B_{n 2}$**: Normal component of $\vec{B}$ in medium 2
- **$\vec{H}$**: Magnetic field intensity
- **$H_1$**: Magnetic field intensity in medium 1
- **$H_2$**: Magnetic field intensity in medium 2
- **$H_{r 1}$**: Tangential component of $\vec{H}$ in medium 1
- **$H_{r 2}$**: Tangential component of $\vec{H}$ in medium 2
- **$\vec{J}$**: Electric current density
- **$J_r$**: Radial component of $\vec{J}$
- **$J_\theta$**: Theta component of $\vec{J}$
- **$J_\psi$**: Azimuthal component of $\vec{J}$
\( \vec{J}_s \)  
\text{Surface current density}

\( I \)  
\text{Electric current}

\( \chi_m \)  
\text{Magnetic susceptibility}

\( \mu \)  
\text{Magnetic permeability}

\( \mu_r \)  
\text{Relative magnetic permeability}

\( \mu_0 \)  
\text{Permeability of free space}

\( \mu_1 \)  
\text{Permeability}

\( \mu_2 \)  
\text{Permeability}

\( \vec{n}_{12} \)  
\text{Unit vector normal to interface; directed from medium 1 into medium 2}

\( x, y, z \)  
\text{Rectangular coordinates}

\( r, \theta, \psi \)  
\text{Spherical coordinates}

\( \hat{e}_r \)  
\text{Unit normal vector in radial direction}

\( \hat{e}_\theta \)  
\text{Unit normal vector in theta direction}

\( \hat{e}_\psi \)  
\text{Unit normal vector in azimuthal direction}

\( \nabla \)  
\text{Divergence operator}

\( \nabla \times \)  
\text{Curl operator}

\( \nabla^2 \)  
\text{Scalar Laplacian operator}

\( \star \)  
\text{Vector Laplacian operator}

\( p \)  
\text{Integer from one to infinity}

\( dv \)  
\text{Elemental volume}

\( r \)  
\text{Radius of spherical coordinate system}

\( r' \)  
\text{Distance of the point where } \vec{A} \text{ is being determined from}

\( P_p^m(\cos \theta) \)  
\text{Associated Legendre function of the first kind}

\( Q_p^m(\cos \theta) \)  
\text{Associated Legendre function of the second kind}

\( c \)  
\text{Speed of light in vacuum}
Azimuthal component of the vector Laplacian of \( \mathbf{A} \) in spherical coordinates

Radial component of the curl of \( \mathbf{A} \)

Theta component of the curl of \( \mathbf{A} \)

Component of radius vector to boundary \( i \) which has spherical symmetry (see Figures 2 and 6)

\( \theta_1, \theta_2 \)

Polar angles describing the limits of the current band

\( A_{p1}, (i = 1, 2, 3), B_{p1}, (i = 2, 3, 4) \)

The constant in the \( r \) part of the solution for the azimuthal component of the vector potential \( \mathbf{A} \) in region \( i \)

\[
A_{\psi i} = \sum_{p=1}^{\infty} \left[ A_{p1} r^p + B_{p1} r^{(p+1)} \right] p^{\perp}(\cos \vartheta)
\]

see equation (28).

\( A', B', C, D \)

The constants in the general solution to the \( r \) and \( \theta \) parts of \( A_{\psi} \)

\[
A_{\psi} = \sum_{p=1}^{\infty} \left[ A'_{p} r^p + B'_{p} r^{(p+1)} \right] p^{\perp}(\cos \theta)
\]

\[
\text{and } \Theta(\theta) = \sum_{p=1}^{\infty} C_{p} p^{\perp}(\cos \theta)
\]

\[
+ D_{p} Q_{p}^{\perp}(\cos \theta), \text{ see equation (25)}
\]

\( A, B \)

The constants in the general solution to the \( r \) part of

\[
A_{\psi} = \sum_{p=1}^{\infty} \left( A_{p} r^p + \frac{B_{p}}{r^{(p+1)}} \right) p^{\perp}(\cos \theta),
\]

see equation (27). Also, \( A_{p} = A'_{p} C_{p} \) and \( B_{p} = B'_{p} C_{p} \)

see (equation 27).
EXECUTIVE SUMMARY

THE MAGNETIC INDUCTION OF THE SYSTEM CONSISTING
OF A COIL AND A FERROMAGNETIC SPHERICAL BODY

OBJECTIVE

The objective of this work was to derive solutions to static ferromagnetic problems that included both current-carrying coils and linear ferromagnetic bodies. The solutions are intended for comparison with solutions to ferromagnetic problems obtained by various numerical techniques such as the finite difference method, the finite element method, and the integral equation iterative solution method.

APPROACH

After deriving the governing differential equation from Maxwell's equations for classical magnetostatic field theory, the method of separation of variables was employed to obtain the problem solution.

RESULTS

The magnetic induction was calculated for two geometries (configurations) of a ferromagnetic spherical body surrounded by a current-carrying conductor. The first case was for an infinitesimally thin current band carrying a stationary current and surrounding a spherical shell. The second case was for a current band of finite width carrying a stationary current and surrounding a solid sphere. The ferromagnetic bodies were assumed to be linear and homogeneous. The reduction of the solution of the dipole term to that of a filamentary, circular, current-carrying conductor is shown for the first case when the permeability of the ferromagnetic spherical shell is allowed to approach that of free space.

RECOMMENDATIONS

It is recommended that the derived solutions be programmed on a digital computer for direct comparison of these results to those obtained by various numerical methods. There are plans to implement these recommendations during the fiscal years 1979 and 1980.
ABSTRACT

The magnetic induction is calculated for two configurations of a ferromagnetic spherical body surrounded by a current-carrying conductor. The first case is for an infinitesimally thin current band carrying a stationary current and surrounding a spherical shell. The second case is for a current band of finite width carrying a stationary current and surrounding a solid sphere. The ferromagnetic bodies are assumed to be linear and homogeneous. The reduction of the solution for the dipole term to that of a filamentary circular current-carrying conductor is shown in the first case when the permeability of the ferromagnetic spherical shell is allowed to approach that of free space.

ADMINISTRATIVE INFORMATION

This work was performed under Program Element 1121N, Project B0005, Task Area B0005-SL-001, Work Unit 2704-110. The project director is Mr. J. L. Corder, David W. Taylor Naval Ship Research and Development Center.

INTRODUCTION

In the past, exact analytical solutions of Maxwell's equations using classical formulations have been limited to body shapes and inhomogeneities that conform to a few separable coordinate systems. With the advent of modern digital computers with large computational and storage capabilities, many electromagnetic field problems of importance in engineering practice can and have been solved by using a numerical solution to the governing differential or integral equations under a suitable choice of boundary conditions. Such numerical solutions of Maxwell's equations, when used with a complete description of the electric and magnetic sources and the constitutive laws of the media, can be used to describe completely the electric and magnetic fields produced by the source, including nonsymmetric geometries, nonsymmetric source distributions, and spatially varying media parameters.
The literature contains numerous examples that demonstrate the power of using numerical techniques such as the finite difference method, the finite element method, and the integral equation iterative solution method. Both two- and three-dimensional electrical engineering problems have been solved. Authors have tried to validate the numerical methods and calculations by comparing numerical results to:

1. Simple problems using engineering approximations.
2. Other numerical method solutions of the same problem.
3. Laboratory experimental results.
4. Problems that have analytical solutions.

Another technique that could be used but which the authors of this report have not seen very widely used in the literature is a comparison of two theoretical formulations for a given problem solved by the same numerical method. An example might be a vector potential formulation compared to a scalar potential formulation.

The motivation for this work arose out of the need for solutions to static ferromagnetic problems that could be used for comparison with numerical methods. The capability exists to calculate the magnetic field due to a ferromagnetic body immersed in a constant inducing field for the following bodies: solid sphere, spherical shell, solid prolate spheroid, prolate spheroidal shell, solid general ellipsoid, and general ellipsoidal shell. Also, the capability exists to calculate the magnetic field caused by a single or combination of current-carrying coils. However, the capability did not exist to calculate the magnetic field caused by a ferromagnetic body in the presence of the field created by a current-carrying coil.

BASIC EQUATIONS

We can start with Maxwell's equations for classical magnetostatic field problems.
\[ \nabla \times \vec{H} = \vec{J} \quad (1a) \star \\
abla \cdot \vec{B} = 0 \quad (1b) \]

where

- \( \vec{H} \) magnetic field intensity (A/m)**
- \( \vec{B} \) magnetic flux density (T or Wb/m²)
- \( \vec{J} \) electric current density (A/m²)

In the general case for ferromagnetic materials \( \vec{B} \) is a nonlinear function of \( \vec{H} \)

\[ \vec{B} = f(\vec{H}) \quad (2) \]

where as shown in Figure 1a \( \vec{B} \) is not a single valued function of \( \vec{H} \). The function \( f(\vec{H}) \) depends on the magnetic history of the material, that is how the metal attained its magnetization. This is referred to as hysteresis. It is also noted that any property of a ferromagnetic material has meaning only if it is considered together with its complete magnetic history.

In certain practical engineering problems, the variation in the magnetic intensity is small, and the functional relationship between \( \vec{B} \) and \( \vec{H} \) is approximately linear (see Figure 1b). For the linear case where the material is isotropic, the magnetic induction \( \vec{B} \) is related to the field intensity \( \vec{H} \) by the relationship

\[ \vec{B} = \mu_0 (\chi_m + 1) \vec{H} = \mu_0 \mu_r \vec{H} = \mu \vec{H} \quad (3) \]

where

- \( \chi_m \) magnetic susceptibility (dimensionless)
- \( \mu \) magnetic permeability (henry/meter)
- \( (\chi_m + 1) = \mu_r \) relative permeability (dimensionless)
- \( \mu_0 \) free space permeability (4πx10⁻⁷ henry/meter)

*The del operator \( \nabla \) is defined with respect to the rectangular coordinate system and is strictly valid in a rectangular coordinate system only. Very often \( \nabla \times \) and \( \nabla \cdot \) are used as equivalent symbols for curl and divergence generally. This use is followed in this report.

**Definitions of abbreviations are on page v.
Figure 1 - Typical Magnetization
This report assumes that the ferromagnetic body has isotropic and linear material properties. The divergenceless nature of the magnetic flux density in conjunction with the fact that the divergence of the curl of any vector function is zero allows the introduction of the magnetic vector potential field \( \mathbf{A} \)

\[
\mathbf{B} = \nabla \times \mathbf{A}
\]

(4)

where \( \mathbf{A} \) is the magnetostatic vector potential function in weber/meter.

The substitution of equation (4) into equation (1a) gives the fundamental equation of the vector potential of the magnetostatic field.

\[
\frac{1}{\mu} \nabla \times (\nabla \times \mathbf{A}) - (\nabla \times \mathbf{A}) \times \nabla \frac{1}{\mu} = \mathbf{J}
\]

(5)

For homogeneous materials as assumed in this report the magnetic permeability is spatially invariant. Hence

\[
\nabla \cdot \mathbf{A} = 0
\]

(6)

and equation (5) reduces to

\[
\nabla \times \nabla \times \mathbf{A} = \mu \mathbf{J}
\]

(7)

Using the vector identity

\[
\nabla \times \nabla \times \mathbf{A} = \nabla (\nabla \cdot \mathbf{A}) - \nabla \times \mathbf{A}
\]

(8)

equation (7) becomes

\[
\nabla (\nabla \cdot \mathbf{A}) - \nabla \times \mathbf{A} = \mu \mathbf{J}
\]

(9)

The magnetostatic vector potential is characterized by the important property that its divergence can be conveniently chosen to be zero.

\[
\nabla \cdot \mathbf{A} = 0
\]

(10)

Equation (9) reduces to the vector Poisson's differential equation.

\[
\nabla^2 \mathbf{A} = - \mu \mathbf{J}
\]

(11)

This is the governing equation for our calculations.
The general boundary conditions to be satisfied at the interfaces of stationary dissimilar media may be derived from the limiting integral forms of Maxwell's equations and are given by

\[ \mathbf{n}_{12} \cdot (\mathbf{B}_2 - \mathbf{B}_1) = 0 \text{ or } B_{n1} = B_{n2} \]  
(12a)

\[ \mathbf{n}_{12} \times (\mathbf{H}_2 - \mathbf{H}_1) = J_s \text{ or } H_{t2} - H_{t1} = J_s \]  
(12b)

where the subscripts 1 and 2 indicate the media under consideration, and \( \mathbf{n}_{12} \) denotes the unit normal vector to the interface and is directed from medium 1 into medium 2. In the case where the materials are linear and isotropic equations (12a) and (12b) become

\[ \mathbf{n}_{12} \cdot (\mu_2 \mathbf{H}_2 - \mu_1 \mathbf{H}_1) = 0 \]  
(12c)

\[ \mathbf{n}_{12} \times \left( \frac{\mathbf{B}_2}{\mu_2} - \frac{\mathbf{B}_1}{\mu_1} \right) = J_s \]  
(12d)

\( J_s \) is a true surface current density that may exist at the interface. At an interface where \( J_s \) is 0, equations (12b) and (12d) need to be modified accordingly.

THIN COIL SURROUNDING A FERROMAGNETIC SPHERICAL SHELL

GENERAL SOLUTION

We now proceed to solve the boundary value problem of a ferromagnetic spherical shell of outer radius \( R_2 \), inner radius \( R_1 \), and a homogeneous permeability \( \mu_2 \), surrounded by an infinitesimally thin current band of radius \( R_3 \) having a current density \( \mathbf{J} \). A constant current density is assumed. Figure 2 identifies the four regions of interest. Regions I, III, and IV have a permeability equal to the permeability of free space \( \mu_0 \) which for convenience will be labeled \( \mu_1 \). The problem's spherical symmetry suggests that a spherical coordinate system such as that shown in Figure 3 be used in the problem solution.
Figure 2 - Ferromagnetic Spherical Shell
Surrounded by an Infinitesimally Thin
Current Band
Figure 3 - Spherical Coordinate System and the Corresponding Unit Vectors
Ampere's law states

\[ \nabla \times \mathbf{H} = \mathbf{J} \]  

(13)

and since \[ \nabla \cdot \mathbf{B} = 0 \], the induction \( \mathbf{H} \) must be the curl of some vector field \( \mathbf{A} \). The governing differential equation for \( \mathbf{A} \) when homogenous and linear material are considered is from equation (11).

\[ \mathbf{A} = -\mu J * \]  

(14)

*We note that a distinction is drawn between the operator \( \nabla^2 \) called the scalar Laplacian operator and the vector Laplacian operator designed by \( \mathcal{A} \). The vector Poisson's equation in rectangular coordinates can be treated as three uncoupled scalar equations as shown below.

\[
\mathcal{A} \mathbf{A}_i = \mathbf{e}_x \left[ \frac{\partial^2 \mathbf{A}_i}{\partial x^2} + \frac{\partial^2 \mathbf{A}_i}{\partial y^2} + \frac{\partial^2 \mathbf{A}_i}{\partial z^2} \right] + \mathbf{e}_y \left[ \frac{\partial^2 \mathbf{A}_i}{\partial x^2} + \frac{\partial^2 \mathbf{A}_i}{\partial y^2} + \frac{\partial^2 \mathbf{A}_i}{\partial z^2} \right] + \mathbf{e}_z \left[ \frac{\partial^2 \mathbf{A}_i}{\partial x^2} + \frac{\partial^2 \mathbf{A}_i}{\partial y^2} + \frac{\partial^2 \mathbf{A}_i}{\partial z^2} \right] = \mathbf{e}_x J_x + \mathbf{e}_y J_y + \mathbf{e}_z J_z
\]

where \( \mathcal{A} \mathbf{A}_i = \nabla^2 \mathbf{A}_i = \mu J_i \) for \( i = x, y, z \). However, if the vector Poisson's equation is resolved into orthogonal components in other coordinate systems the differential operation mixes the components together giving coupled equations as shown below for spherical coordinates.

\[
\mathcal{A} \mathbf{A}_i = \mathbf{e}_r \left[ \frac{\partial^2 \mathbf{A}_i}{\partial r^2} + \frac{2}{r} \frac{\partial \mathbf{A}_i}{\partial r} - \frac{2}{r^2} \mathbf{A}_i + \frac{1}{r^2} \frac{\partial^2 \mathbf{A}_i}{\partial \theta^2} + \frac{\cot \theta}{r^2} \frac{\partial \mathbf{A}_i}{\partial \theta} + \frac{1}{r^2 \sin \theta} \frac{\partial^2 \mathbf{A}_i}{\partial \phi^2} \right] + \mathbf{e}_\theta \left[ \frac{\partial^2 \mathbf{A}_i}{\partial r^2} + \frac{2}{r} \frac{\partial \mathbf{A}_i}{\partial r} - \frac{\partial^2 \mathbf{A}_i}{\partial \theta^2} + \frac{\cot \theta}{r^2} \frac{\partial \mathbf{A}_i}{\partial \theta} + \frac{1}{r^2 \sin \theta} \frac{\partial^2 \mathbf{A}_i}{\partial \phi^2} \right] + \mathbf{e}_\phi \left[ \frac{\partial^2 \mathbf{A}_i}{\partial r^2} + \frac{2}{r} \frac{\partial \mathbf{A}_i}{\partial r} - \frac{\partial^2 \mathbf{A}_i}{\partial \theta^2} + \frac{\cot \theta}{r^2} \frac{\partial \mathbf{A}_i}{\partial \theta} + \frac{1}{r^2 \sin \theta} \frac{\partial^2 \mathbf{A}_i}{\partial \phi^2} \right]
\]
The general expression in spherical coordinates for a current density is

\[ \mathbf{J} = \mathbf{e}_r J_r + \mathbf{e}_\theta J_\theta + \mathbf{e}_\psi J_\psi \]  

(15)

where the \( \mathbf{e}_r, \mathbf{e}_\theta, \mathbf{e}_\psi \) are the unit orthogonal vectors. For stationary currents in vacuum the vector potential function that satisfies equation (14) is given by

\[ \mathbf{A} = \frac{\mu_0}{4\pi} \int \frac{\mathbf{J}}{r'} \, dv \]  

(16)

where \( dv \) = elemental volume in the current-carrying region

\[ r' = \text{distance between the field point where } \mathbf{A} \text{ is being determined and } dv \text{ at the source point.} \]

From equation (16), we see that the elemental vector potential \( d\mathbf{A} \) due to a current element \( d\mathbf{J}dv \) is in the same direction as \( \mathbf{J} \). It is well known from this that the lines of the magnetic vector potential \( \mathbf{A} \) are circles centered about the coil or loop axis. The magnitude of \( \mathbf{A} \) along such a circle is constant, which means that \( \mathbf{A} \) is a function of the spherical coordinates \( r \) and \( \theta \) only. Therefore, we know in advance for this problem that \( A_\psi \) is the only component of \( \mathbf{A} \) existing at the field point. The infinitesimally thin band of current shown in Figure 2 has only an azimuthal or \( \psi \) component, which is a function of \( r \) and \( \theta \), and lies on the boundary between regions III and IV (i.e. \( r = R_3 \)). For this current, equation (15) reduces to

\[ \mathbf{J} = \begin{cases} 0 & \text{if } \theta < \theta_1 \text{ or } \theta > \theta_2 \\ \mathbf{e}_\psi J_\psi(\theta) & \text{if } \theta_1 \leq \theta \leq \theta_2 \end{cases} \]  

(17)

Therefore, equation (14) has only an azimuthal component and can be expressed as:
\[ \Box A_{\psi} = \Box A_{\psi}(r, \theta) = 0 \text{ (in regions I through IV)} \quad (18) \]

When the vector Laplacian \( \Box \) is expanded in spherical coordinates, equation (18) can be written as

\[
\frac{\partial^2 A_{\psi}}{\partial r^2} + \frac{1}{r} \frac{\partial A_{\psi}}{\partial r} + \frac{1}{r^2} \frac{\partial^2 A_{\psi}}{\partial \theta^2} + \frac{\cot \theta}{r^2} \frac{\partial A_{\psi}}{\partial \theta} - \frac{A_{\psi}}{r^2 \sin^2 \theta} = 0 \text{ in regions I through IV} \quad (19)
\]

In order to solve equation (19), it is necessary to obtain the general solution in regions I through IV. Thus, by multiplying equation (19) by \( r^2 \) we obtain

\[
\frac{r^2 \partial^2 A_{\psi}}{\partial r^2} + \frac{2r \partial A_{\psi}}{\partial r} + \frac{\partial^2 A_{\psi}}{\partial \theta^2} + \frac{\cot \theta}{r^2} \frac{\partial A_{\psi}}{\partial \theta} - \frac{A_{\psi}}{r^2 \sin^2 \theta} = 0 \quad (20)
\]

Applying the method of separation of variables, let us assume that \( A_{\psi} \) can be expressed as a product of two functions

\[ A_{\psi} = R(r) \Theta(\theta) \quad (21) \]

where \( R(r) \) is a function of \( r \) only and \( \Theta(\theta) \) of \( \theta \) only. Substituting this form of the vector potential \( A_{\psi} \) into equation (20), we have after separation of variables

\[
\frac{d^2 R(r)}{dr^2} + \frac{2}{r} \frac{dR(r)}{dr} - \frac{P(p+1)R(r)}{r^2} = 0 \quad (22a)
\]

\[
\frac{d^2 \Theta(\theta)}{d\theta^2} + \cot \theta \frac{d\Theta(\theta)}{d\theta} + \left[ p(p+1) - \frac{1}{\sin^2 \theta} \right] \Theta(\theta) = 0 \quad (22b)
\]

where the separation constant is \( p(p+1) \) and \( p \) is an integer from one to infinity. The differential equation
\[
\frac{d^2 \Theta}{d\theta^2} + \cot \theta \frac{d\Theta}{d\theta} + \left[ p(p+1) - \frac{m^2}{\sin^2 \theta} \right] \Theta = 0 \quad (23)
\]

has as a general solution

\[
\Theta(\theta) = \Theta_p(\theta) = C_p P_p^m(\cos \theta) + D_p Q_p^m(\cos \theta) \quad (24)
\]

Comparison of equations (22b) and (23) shows that in equation (23) \( m^2 \) is equal to 1. This requires that \( m \) always be unity. The solutions of equations (22a) and (22b) are then expressed as

\[
R(r) = R_p(r) = A'_p r^p + B'_p r^{-(p+1)}
\]

\[
\Theta(\theta) = \Theta_p(\theta) = C_p P_p^1(\cos \theta) + D_p Q_p^1(\cos \theta)
\]

The associated Legendre functions of the first and second kind are designated as \( P_p^m(\cos \theta) \) and \( Q_p^m(\cos \theta) \), respectively. Therefore, the general solution of equation (19) in regions I through IV may be formed from the product of the solutions in equation (25) which yields

\[
A_p = R(r)\Theta(\theta) = \sum_{p=1}^{\infty} R_p(r)\Theta_p(\theta)
\]

\[
= \sum_{p=1}^{\infty} \left( A'_p r^p + \frac{B'_p}{r^{p+1}} \right) \left( C_p P_p^1(\cos \theta) + D_p Q_p^1(\cos \theta) \right) \quad (26)
\]

In the spherical case, associated Legendre functions of the second kind are infinite at \( \cos \theta = \pm 1 \), and thus cannot be included when the region under consideration includes the symmetry axis. Therefore, the constant \( D_p \) must be set equal to zero, and equation (26) reduces to

\[
A_p = \sum_{p=1}^{\infty} \left( A'_p r^p + \frac{B'_p}{r^{p+1}} \right) P_p^1(\cos \theta)
\]

where

\[
A_p = A'_p C_p, \quad B_p = B'_p C_p \quad (27)
\]
BOUNDARY CONDITIONS

The form of the potential in each of the regions (I through IV) is determined from equation (27). These magnetostatic vector potentials in regions I—IV are:

\[ A_I = A_{ψI} = \sum_{p=1}^{∞} (A_p r^p) \frac{P_p(\cosθ)}{r} \]

\[ A_{II} = A_{ψII} = \sum_{p=1}^{∞} \left[ A_p r^p + \frac{B_p}{r(p+1)} \right] \frac{P_p(\cosθ)}{r} \]

\[ A_{III} = A_{ψIII} = \sum_{p=1}^{∞} \left[ A_p r^p + \frac{B_p}{r(p+1)} \right] \frac{P_p(\cosθ)}{r} \]

\[ A_{IV} = A_{ψIV} = \sum_{p=1}^{∞} \frac{B_p}{r(p+1)} \frac{P_p(\cosθ)}{r} \]

where for the \( A_{ψI} \) component \( B_{p1} = 0 \) because at \( r = 0 \) the potential must be finite and for the \( A_{ψIV} \) component \( A_{p4} = 0 \) because as \( r \) approaches infinity the potential must remain finite.

At each interface, the basic laws of magnetostatics in equations (1a) and (1b) reduce to boundary conditions on \( B \) and \( H \) that can be used to evaluate the six constants in equation (28). From equation (1b), the normal component of \( B \) across each boundary must be continuous, i.e., \((B_2 - B_1) \cdot \hat{n}_{12} = 0\)

where the quantity \( \hat{n}_{12} \) is the unit outward normal to the surface. This provides the following boundary conditions which must be satisfied by the solution in equation (28) for each region.

\[ B_{rI} = B_{rII} \quad \text{at} \quad r = R_1 \]

\[ B_{rII} = B_{rIII} \quad \text{at} \quad r = R_2 \]

\[ B_{rIII} = B_{rIV} \quad \text{at} \quad r = R_3 \]
The normal component of the magnetic field $B_r$ is expressed in terms of the vector potential as

$$B_r = (\nabla \times A)_r$$

or

$$B_r = \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta A_\theta)$$

where

$$\vec{B} = \nabla \times \vec{A} = \frac{1}{r \sin \theta} \begin{vmatrix} e_r & e_\theta & e_\psi \sin \theta \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \psi} \\ 0 & 0 & A_\psi r \sin \theta \end{vmatrix}$$

However, since the vector potentials in each region are functions of $P_1(\cos \theta)$ we can simplify equation (29) to constraints on $A_\psi$

$$A_I = A_{II} \text{ at } r = R_1$$

$$A_{II} = A_{III} \text{ at } r = R_2$$

$$A_{III} = A_{IV} \text{ at } r = R_3$$

The second set of boundary conditions is obtained from equation (12b). The tangential component of $H$ across each boundary must satisfy the relationship

$$\vec{n}_{12} \times (\vec{H}_2 - \vec{H}_1) = J_s$$

where $J_s$ (which equals $J(\theta)$) is the real surface current density in the limit of vanishing width between the two regions. Using the relationship $B = \mu H$, equation (32) may be expressed as

$$\frac{B_{02}}{\mu_2} - \frac{B_{01}}{\mu_1} = J(\theta)$$
Referring to the curl in equation (30), we can write $B_\theta$ as

$$B_\theta = \nabla \times A_\theta = -\frac{1}{r} \frac{\partial}{\partial r} \left[ r A_\psi \right] \quad (34)$$

From equations (32), (33), and (34) the tangential components in regions I–IV must satisfy the relationships.

$$-\frac{1}{\mu_2} \frac{1}{r} \frac{\partial}{\partial r} (r A_{II}) + \frac{1}{\mu_1} \frac{1}{r} \frac{\partial}{\partial r} (r A_I) = 0 \text{ at } r = R_1 \quad (35a)$$

$$-\frac{1}{\mu_1} \frac{1}{r} \frac{\partial}{\partial r} (r A_{III}) + \frac{1}{\mu_2} \frac{1}{r} \frac{\partial}{\partial r} (r A_{II}) = 0 \text{ at } r = R_2 \quad (35b)$$

$$-\frac{1}{\mu_1} \frac{1}{r} \frac{\partial}{\partial r} (r A_{IV}) + \frac{1}{\mu_1} \frac{1}{r} \frac{\partial}{\partial r} (r A_{III}) = \mathbf{J}(\theta) \text{ at } r = R_3 \quad (35c)$$

The general expressions for the potentials in each region (equation (28)) are then substituted into the boundary conditions (equations (31) and (35)) and solved for the constants $A_{p1}$ and $B_{p1}$. There are six algebraic equations with six unknowns and the potential in each region can then be specifically determined. The six boundary value equations that must be solved for the coefficients are given below (where the index $p$ is odd only and understood to take on values from 1 to $\infty$). It is noted that the current $J_\psi(\theta)$ must be expanded into a set of associated Legendre functions in order to evaluate the constants $A_{p1}$ and $B_{p1}$. The detailed expansion is in the next section entitled "Expansion of the Current ($J_\psi(\theta)$) in Associated Legendre Polynomials".

$$A_{p1} R_1^p \equiv \left[ A_{p2} R_1^p + B_{p2} R_1^{-(p+1)} \right] \quad (36a)$$

$$\left[ A_{p3} R_2^p + B_{p3} R_2^{-(p+1)} \right] = \left[ A_{p3} R_2^p + B_{p3} R_2^{-(p+1)} \right] \quad (36b)$$

$$\left[ A_{p3} R_3^p + B_{p3} R_3^{-(p+1)} \right] = B_{p4} \left[ R_3^{-(p+1)} \right] \quad (36c)$$
The solution of these equations to obtain $B_{p3}$ in terms of known quantities is performed in Appendix A. In summary:

\[
B_{p3} = \frac{- \frac{1}{\nu_2} \left[ \frac{A_{p2}(p+1)}{p} \left( R_{1}^{p-1} - pB_{p2}R_{1}^{p-2} \right) + \frac{1}{\nu_1} \left[ \frac{A_{p1}(p+1)}{p} R_{1}^{p-1} \right] \right]}{\left[ \left( \frac{1}{\nu_1} (p)R_{2}^{p-2} \right) + \frac{1}{\nu_2} \left( [Z][X] (p+1)R_{2}^{p-1} \right) - \frac{1}{\nu_2} \left( [Z] (p)R_{2}^{p-2} \right) \right]}
\]

where

\[
[X] = \frac{-R_{1}^{-(2p+1)} \left[ 1 + \left( \frac{p}{p+1} \right) \frac{\nu_1}{\nu_2} \right]}{\left( 1 - \frac{\nu_1}{\nu_2} \right)}
\]

\[
[Z] = \frac{R_{2}^{-p-1}}{\left( [X] R_{1}^{p} + R_{2}^{-(p+1)} \right)}
\]

(36d)
The numerical values for the other five coefficients can be obtained from
the following equations:

\[ B_{p2} = B_{p3} [Z] + J_P''(\theta) \]  \hspace{1cm} (38a)

\[ A_{p3} = J_P'(\theta) \]  \hspace{1cm} (38b)

\[ A_{p2} = [X] B_{p2} \]  \hspace{1cm} (38c)

\[ A_{p1} = A_{p2} + B_{p2} R_1^{-(2p+1)} \]  \hspace{1cm} (38d)

\[ B_{p4} = A_{p3} R_3^{(2p+1)} + B_{p3} \]  \hspace{1cm} (38e)

Since the coefficients \( A_{p1} \) and \( B_{p1} \) can be determined from equations (37) and (38), equations (28) can now be used to completely specify the potentials \( A_I, A_{II}, A_{III}, \) and \( A_{IV} \) in regions I through IV. Then the normal \((B_r)\) and tangential \((B_\theta)\) components of the magnetic induction in regions I through IV can be determined by using equations (30) and (34), respectively.

In Appendix B the magnetic vector potentials \( A_{\psi I} \) in the inner region and \( A_{\psi II} \) in the outer region are derived for the infinitesimally thin current band in a homogeneous medium of permeability \( \mu \) (see Figure 1-B in Appendix B). Also, the dipole potential term in the outer region \((r>R_1)\) for the infinitesimally thin current band is reduced in a special case to the dipole potential term for the circular filamentary current loop.
In Appendix C the coefficients \( A_i (i = 1, 2, 3) \) and \( B_i (i = 2, 3, 4) \) for the vector potentials for the present ferromagnetic shell problem reduce to the potentials in the two regions of the simple current band problem when the permeability of the ferromagnetic shell \( \mu_2 \) approaches that of the surrounding medium \( \mu_1 \). This shows that the solutions of the above ferromagnetic current problem have the correct mathematical form.

EXPANSION OF THE CURRENT \( (J_\psi(\theta)) \) IN ASSOCIATED LEGENDRE POLYNOMIALS

Any function that can be expanded using a Fourier's series in a given interval \(-1 < \mu'^2 < 1\) can also be expanded in a series of associated Legendre polynomials in the same interval using similar methods. The associated Legendre functions are defined by the equation

\[
\frac{d^m P_\mu (\mu' \, | \, \mu'^2)}{d\mu'^m} = (1 - \mu'^2)^{\frac{m}{2}} P_\mu (\mu')
\]

where \( \mu' = \cos \theta \) and \(-1 < \mu' < 1\). Also, the function \( P_\mu (\mu') \), which is valid whatever the range of the variable \( \mu' \), is defined as

\[
P_\mu (\mu') = \frac{1}{2^n \mu^n} \frac{d^n P_\mu (\mu'^2 - 1)}{d\mu'^n}
\]

Let us assume the expansion is similar to Purczyński's

\[
J_\psi(\theta) = \sum_{p=1}^{\infty} J_p K_p \frac{1}{p} (\cos \theta)
\]

The coefficients \( K_p \) are determined from equation (41) by multiplying both sides by \( \frac{1}{p} (\cos \theta) \) and integrating over \( \sin \theta \, d\theta \) from 0 to \( \pi \).

\[
K_p = \frac{(2p+1)}{2p(p+1)} \cdot \frac{1}{J} \cdot \int_{0}^{\pi} J_\psi(\theta) \frac{1}{p} (\cos \theta) \sin \theta \, d\theta
\]
The identity
\[ \int_0^\pi p_p^m(\cos \theta) p_p^m(\cos \theta) \sin \theta d\theta = \frac{2(\ell+1)}{(2\ell+1)(\ell+1)!} \delta_p^\ell \delta_m^\ell \]  \hspace{1cm} (43)

was used to determine \( K_p \) (equation 42). Setting \( J_\psi(\theta) \) to a constant \( J \) we can express equation (42) as:

\[ K_p = \frac{2p+1}{2p(p+1)} \int_0^\pi p_p^1(\cos \theta) \sin \theta d\theta \]  \hspace{1cm} (44)

Since the current in this problem extends from \((\pi/2 - \alpha)\) to \((\pi/2 + \alpha)\), see Figure 4, the expression for \( K_p \) (equation 44) may be written as:

\[ K_p = \frac{2p+1}{2p(p+1)} \left[ \int_{\pi/2 - \alpha}^{\pi/2} p_p^1(\cos \theta) \sin \theta d\theta + \int_{\pi/2 + \alpha}^{\pi/2} p_p^1(\cos \theta) \sin \theta d\theta \right] \]  \hspace{1cm} (45)

By noting that
\[ p_p^1(-\cos \theta) = (-1)^p p_p^1(\cos \theta) \]  \hspace{1cm} (46)

it follows that the associated Legendre functions \( p_p^1(\cos \theta) \) are even functions with respect to \( \cos \theta \) when \( p \) is odd. The expression for \( K_p \) may be simplified to

\[ K_p = \frac{2p+1}{p(p+1)} \int_{\pi/2 - \alpha}^{\pi/2} p_p^1(\cos \theta) \sin \theta d\theta. \]  \hspace{1cm} (47)

when \( p \) is odd (\( K_p = 0 \) when \( p \) is even) after utilizing the symmetry of \( J(\theta) \) in Figure 5. By changing the variable in equation (47) to \( u' = \cos \theta \), the integral for \( K_p \) may be written as

\[ K_p = \frac{2p+1}{p(p+1)} \int_0^{\sin \alpha} p_p^1(u') du' \]  \hspace{1cm} (48)
The values of the coefficients $K_p$ for $p$ odd were worked out by Purczynski and are:

1. $K_1 = \frac{3}{4} (\sin \alpha \cos \alpha + \alpha)$  
   \hspace{2cm} (49a)

2. $K_3 = \frac{7}{64} (\sin \alpha \cos \alpha (10 \sin^2 \alpha - 9) + \alpha)$  
   \hspace{2cm} (49b)

3. $K_5 = \frac{11}{256} (\sin \alpha \cos \alpha (56 \sin^4 \alpha - 70 \sin^2 \alpha + 15) + \alpha)$  
   \hspace{2cm} (49c)

4. $K_7 = \frac{15}{32768} (\sin \alpha \cos \alpha (13728 \sin 6 \alpha - 23408 \sin 2 \alpha + 15) + 50 \alpha)$  
   \hspace{2cm} (49d)

5. $K_9 = \frac{19}{327680} (\sin \alpha \cos \alpha (311168 \sin 8 \alpha - 679536 \sin 6 \alpha + 488488 \sin 2 \alpha + 128590 \sin 2 \alpha + 8715) + 245 \alpha)$  
   \hspace{2cm} (49e)

Figure 4 - Spherical Coil Cross-Sectional View - Definition of Angle Alpha
Figure 5 - Coil Current as a Function of the Polar Angle Theta

FERROMAGNETIC SPHERE SURROUNDED BY A COIL OF FINITE WIDTH

GENERAL SOLUTION

We now proceed to solve the boundary value problem of a solid ferromagnetic sphere of radius $R_1$ and homogeneous permeability $\mu_1$ surrounded by a current band of finite width having inner radius $R_2$ and outer radius $R_3$ as shown in Figure 6. A constant current density is assumed. A linear relationship between $B$ and $H$ is assumed. Regions II, III, and IV have homogeneous free space permeability designated as $\mu_2$. The permeability of the conducting coil in region III is assumed, also, to be equal to $\mu_2$. The geometry of the problem suggests spherical symmetry as in the previous problem.

The partial differential equation that governs this problem is again equation (11),

$$\nabla \times \begin{pmatrix} A_x \\ A_y \end{pmatrix} = -\mu J$$

where

$$A_x = e_y A(y, \theta)$$

$$A_y = e_y J_y (r, \theta)$$

$$J = e_y J_y (r, \theta)$$

(50)
As before, it is necessary to solve equation (50) and use the appropriate boundary conditions to evaluate the constants. Equation (50) reduces to

\[ \mathbf{A}_\psi = -\mu J_\psi (r, \theta) \]  

(51)

where

\[ J_\psi (r, \theta) = J_\psi (\theta) \]  in region III if \( \theta_1 \leq \theta \leq \theta_2 \) and \( R_2 < r < R_3 \)

\[ J_\psi (\theta) = 0 \]  if \( \theta < \theta_1 \) or \( \theta > \theta_2 \) for all \( r \) (\( \theta_1 \) and \( \theta_2 \) are defined in Figure 6).
Expanding the vector Laplacian in equation (51) in spherical coordinates results in the expression:

\[
\frac{\partial^2 A_\psi}{\partial r^2} + \frac{2}{r} \frac{\partial A_\psi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 A_\psi}{\partial \theta^2} + \frac{\cot \theta}{r^2} \frac{\partial A_\psi}{\partial \theta} - \frac{A_\psi}{r^2 \sin^2 \theta} =
\]

\[\begin{cases}
\mu J_\psi (\theta) & \text{in region III} \\
0 & \text{in regions I, II, and IV}
\end{cases}\]

Thus, the solutions in regions I, II, and IV are solutions of Laplace's equation and are obtained by the method of separation of variables as in the previous problem. The potential solution in region III, however, is the solution of Poisson's equation.

The potentials in regions I, II, III, and IV are:

\[
A_I = \psi_I = \sum_{p=1}^{\infty} \left( A_{p1} r^P \right) P^1_0 (\cos \theta)
\]

\[
A_{II} = \psi_{II} = \sum_{p=1}^{\infty} \left( A_{p2} r^P + \frac{B_{p2}}{r(p+1)} \right) P^1_p (\cos \theta)
\]

\[
A_{III} = \psi_{III} = \sum_{p=1}^{\infty} \left( A_{p3} r^P + \frac{B_{p3}}{r(p+1)} \right) P^1_p (\cos \theta) + \sum_{p=2}^{\infty} \left( \frac{\mu_2 J_\psi r^2 \frac{K_p}{p}}{r(p-2)(p+3)} \right) P^1_p (\cos \theta)
\]

\[
A_{IV} = \psi_{IV} = \sum_{p=1}^{\infty} \left( \frac{B_{p4}}{r(p+1)} \right) P^1_p (\cos \theta)
\]

Equation (53c), the azimuthal component of Poisson's equation in spherical coordinates, is solved in detail in Appendix D. When the current is expanded in associated Legendre functions we have
\begin{equation}
J_\psi(r,\theta) = J(\theta) = J \sum_{p=1}^{\infty} \kappa_p p^1(\cos \theta) \tag{54}
\end{equation}

where only the odd coefficients contribute since the even coefficients are zero. The coefficients for the current were derived previously (see equations (49a through 49e)).

BOUNDARY CONDITIONS

This solution must satisfy the boundary conditions developed in equations (29) through (33). Because there are no surface currents on the boundary between the regions in this ferromagnetic problem, \( J_s \) is zero and the tangential boundary conditions for regions I-IV become

\begin{equation}
\frac{1}{\mu_2} \frac{1}{r} \frac{\partial}{\partial r} (r A_{II}(r,\theta)) = \frac{1}{\mu_1} \frac{1}{r} \frac{\partial}{\partial r} (r A_I(r,\theta)) \text{ at } r = R_1 \tag{55a}
\end{equation}

\begin{equation}
\frac{1}{\mu_2} \frac{1}{r} \frac{\partial}{\partial r} (r A_{III}(r,\theta)) = \frac{1}{\mu_2} \frac{1}{r} \frac{\partial}{\partial r} (r A_{II}(r,\theta)) \text{ at } r = R_2 \tag{55b}
\end{equation}

\begin{equation}
\frac{1}{\mu_2} \frac{1}{r} \frac{\partial}{\partial r} (r A_{IV}(r,\theta)) = \frac{1}{\mu_2} \frac{1}{r} \frac{\partial}{\partial r} (r A_{III}(r,\theta)) \text{ at } r = R_3 \tag{55c}
\end{equation}

The general expressions for the potentials in each region (equation (53)) are then substituted into the boundary conditions (equations (31) and (55)) and solved for the \( A_{p1}'s \) and \( B_{p1}'s \). There are six algebraic equations with six unknowns and the potential in each region can then be specifically determined. The six boundary conditions that must be solved for the coefficients are (where the index \( p \) is odd only and understood to take the values 1 to \( \infty \)):

\begin{equation}
A_{p1}'R_1^p = A_{p2}'R_1^p + B_{p2}'R_1^{-(p+1)} \tag{56a}
\end{equation}

24
\[
A_{p_2} R_{2}^p + B_{p_2} R_{2}^{-(p+1)} = A_{p_3} R_{2}^p + B_{p_3} R_{2}^{-(p+1)} + \frac{\mu_2 J R_2}{(p-2)(p+3)} K_p
\] (56b)

\[
A_{p_3} R_{3}^p + B_{p_3} R_{3}^{-(p+1)} + \frac{\mu_2 J R_2}{(p-2)(p+3)} K_p = B_{p_4} R_{3}^{-(p+1)}
\] (56c)

\[
\frac{1}{\mu_2} \left[ A_{p_2} (p+1) R_{1}^{p-1} - (p) B_{p_2} R_{1}^{-p-2} \right] = \frac{1}{\mu_1} \left[ A_{p_1} (p+1) R_{1}^{p-1} \right]
\] (56d)

\[
\frac{1}{\mu_2} \left[ A_{p_3} (p+1) R_{2}^{p-1} - (p) B_{p_3} R_{2}^{-p-2} + \frac{3\mu_2 J R_2 K_p}{(p-2)(p+3)} \right]
\] (56e)

\[
\frac{1}{\mu_2} \left[ - (p) B_{p_4} R_{3}^{-p-2} \right] = \frac{1}{\mu_2} \left[ A_{p_3} (p+1) R_{3}^{p-1} - (p) B_{p_3} R_{3}^{-p-2} + \frac{3\mu_2 J R_2 K_p}{(p-2)(p+3)} \right]
\] (56f)

The mathematical solution for \( B_{p_3} \) in terms of known quantities obtained in Appendix E and is given by

\[
B_{p_3} = \left\{ \begin{array}{c}
-K_p (p+1) R_2^{(p-1)} - \frac{3\mu_2 J R_2 K_p}{(p-2)(p+3)} \\
+ [X] (p+1) R_2^{p-1} K_{p}^{i+i} - (p) R_2^{-p-2} K_{p}^{i+i} \\
- (p) R_2^{-p-2} - [Z][X] (p+1) R_2^{p-1} + [Z] (p) R_2^{-p-2}
\end{array} \right\}
\] (57a)
\[ [x] = - \frac{R_1}{R_1} \left( \frac{1}{1 + \frac{p}{p+1} \frac{\mu_1}{\mu_2}} \right) \]

\[ K_{p}^{'} = - \frac{\mu_2 J K R_3}{(p-2)(2p+1)} \]

\[ [z] = \frac{R_2}{(X) R_2^p + R_2^{-(p+1)}} \]

\[ K_{p}''' = \frac{\mu_2 J R_2^2 K}{(p-2)(p+3)} \frac{R_2^p}{R_2^{-(p+1)}} \]

The numerical values for the other coefficients can be obtained from the equations:

\[ A_{p3} = K_{p}^{'} \]

\[ B_{p2} = B_{p3} [z] + K_{p}''' \]

\[ A_{p2} = [x] B_{p2} \]

\[ A_{p1} = A_{p2} + B_{p2} R_1^{-(2p+1)} \]

\[ B_{p4} = A_{p3} R_3^{(2p+1)} + B_{p3} + \frac{\mu_2 J R_3^{(p+3)k}}{(p-2)(p+3)} \]
CONCLUSIONS AND RECOMMENDATIONS

The method of separation of variables has been applied to determine the magnetic field of the systems consisting of an infinitesimally thin spherical coil around (outside) a ferromagnetic spherical shell and a spherical current band of finite width around a solid ferromagnetic sphere. The resulting formulae can be used in the analysis of magnetic induction of ferromagnetic bodies due to current-carrying coils.

The magnetic vector potentials in the inner and outer regions are derived for the infinitesimally thin current band in a medium of homogeneous permeability. The dipole term for the potential on the outer region for the infinitesimally thin current band is reduced in a special case to the dipole potential term for the circular filamentary current loop. It is also shown that the vector potential for the ferromagnetic shell surrounded by a infinitesimally thin current band reduce to the potential in the two regions of the simple current band problem when the permeability of the ferromagnetic shell approaches that of the surrounding medium.

It is recommended that the solutions derived in this report be programmed on a digital computer. The resulting calculations should then be compared to solutions obtained by various numerical methods in order to validate the numerical methods and calculations. There are plans to implement these recommendations during the fiscal years 1979 and 1980.

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APPENDIX A
CALCULATION OF COEFFICIENTS OF THE VECTOR POTENTIALS FOR A THIN COIL SURROUNDING A FERROMAGNETIC SPHERICAL SHELL

In this appendix the coefficients are derived for the vector potentials in regions I–IV for a ferromagnetic spherical shell surrounded by an infinitely thin current band. For a detailed discussion of the ferromagnetic problem see the section in the text of the report entitled "Thin Coil Surrounding a Ferromagnetic Spherical Shell". The magnetic vector potentials in each region are given by:

\[ A_{\psi I} = \sum_{p=1}^{\infty} \left( A_{p1} r^p \right) P_{p}^1(\cos \theta) \]  
(A-1a)

\[ A_{\psi II} = \sum_{p=1}^{\infty} \left( A_{p2} r^p + \frac{B_{p2}}{r^{(p+1)}} \right) P_{p}^1(\cos \theta) \]  
(A-1b)

\[ A_{\psi III} = \sum_{p=1}^{\infty} \left( A_{p3} r^p + \frac{B_{p3}}{r^{(p+1)}} \right) P_{p}^1(\cos \theta) \]  
(A-1c)

\[ A_{\psi IV} = \sum_{p=1}^{\infty} \left( \frac{B_{p4}}{r^{(p+1)}} \right) P_{p}^1(\cos \theta) \]  
(A-1d)

The coefficients \( A_{p1} \) and \( B_{p4} \) in equations A-1a to A-1d are obtained by substituting these equations into the boundary conditions (equations (A-2a to A-2f)).

\[ A_I = A_{II} \text{ at } r = R_1 \]  
(A-2a)

\[ A_{II} = A_{III} \text{ at } r = R_2 \]  
(A-2b)

\[ A_{III} = A_{IV} \text{ at } r = R_3 \]  
(A-2c)
\[-\frac{1}{\mu_2} \frac{1}{r} \frac{\partial}{\partial r} (rA_{II}) + \frac{1}{\mu_1} \frac{1}{r} \frac{\partial}{\partial r} (rA_{I}) = 0 \quad \text{at} \quad r = R_1 \quad (A-2d)\]

\[-\frac{1}{\mu_1} \frac{1}{r} \frac{\partial}{\partial r} (rA_{III}) + \frac{1}{\mu_2} \frac{1}{r} \frac{\partial}{\partial r} (rA_{II}) = 0 \quad \text{at} \quad r = R_2 \quad (A-2e)\]

\[-\frac{1}{\mu_1} \frac{1}{r} \frac{\partial}{\partial r} (rA_{IV}) + \frac{1}{\mu_2} \frac{1}{r} \frac{\partial}{\partial r} (rA_{III}) = J(\theta) \quad \text{at} \quad r = R_3 \quad (A-2f)\]

After appropriate substitutions of equations A-1a to A-1d into equations A-2a to A-2f, the following boundary value equations are obtained.

\[
\begin{align*}
(A_{p_1} R_1^p) &= \left( A_{p_2} R_1^p + \frac{B_{p_2}}{R_1(p+1)} \right) \quad (A-3a) \\
\left( A_{p_2} R_2^p + \frac{B_{p_2}}{R_2(p+1)} \right) &= \left( A_{p_3} R_2^p + \frac{B_{p_3}}{R_2(p+1)} \right) \quad (A-3b) \\
\left( A_{p_3} R_3^p + \frac{B_{p_3}}{R_3(p+1)} \right) &= \left( \frac{B_{p_4}}{R_3(p+1)} \right) \quad (A-3c) \\
- \frac{1}{\mu_2} \left[ A_{p_2} (p+1) R_1^{p-1} - (p) B_{p_2} R_1^{-p-2} \right] + \frac{1}{\mu_1} \left[ A_{p_1} (p+1) R_1^{p-1} \right] &= 0 \quad (A-3d) \\
- \frac{1}{\mu_1} \left[ A_{p_3} (p+1) R_2^{p-1} - (p) B_{p_3} R_2^{-p-2} \right] + \frac{1}{\mu_2} \left[ A_{p_2} (p+1) R_2^{p-1} - (p) B_{p_2} R_2^{-p-2} \right] &= 0 \quad (A-3e)
\end{align*}
\]
These algebraic equations provide six simultaneous equations with six unknowns, and they can be solved for the coefficients $A_{\text{p}1}$ and $B_{\text{p}1}$ by tedious algebraic manipulation.

Solving equations (A-3a and A-3d) algebraically results in the solution for $A_{\text{p}2}$ in terms of $B_{\text{p}2}$.

$$A_{\text{p}2} = \begin{bmatrix} X \end{bmatrix} B_{\text{p}2}$$

(A-4)

where

$$[X] = \frac{-R_1^{-(2p+1)} \left[ 1 + \left( \frac{P}{p+1} \right) \frac{\mu_1}{\mu_2} \right]}{1 - \frac{\mu_1}{\mu_2}}$$

The solution for $A_{\text{p}1}$ from equation (A-3a) is

$$A_{\text{p}1} = A_{\text{p}2} + B_{\text{p}2}R_1^{-(2p+1)}$$

(A-5)

Also, solving equations (A-3c) and (A-3f) algebraically for $B_{\text{p}4}$ gives the expression for $A_{\text{p}3}$ in terms of known quantities after equating the functions for $B_{\text{p}4}$ to $B_{\text{p}4}$ from each equation. Thus,

$$A_{\text{p}3} = J'_p(\theta)$$

(A-6)

where

$$J'_p(\theta) = \frac{\mu_1 J_p(\theta)}{P \left( \frac{\mu_1}{\mu_2} \right) R_3 (p-1) (2p+1)}$$
The algebraic solution for $B_{p4}$ from equation (A-3c) is

$$B_{p4} = A_{p3} R_3^{(2p+1)} + B_{p3}$$  \hspace{2cm} (A-7)

The following expression is obtained for $B_{p2}$ from equation (A-3b) after substituting the expressions for $A_{p3}$ (equation A-6), and $A_{p2}$ (equation A-4).

$$B_{p2} = B_{p3} \left[ Z \right] + J_p^{\mu}(\theta)$$  \hspace{2cm} (A-8)

where

$$[Z] = \frac{R_2^{-(p+1)}}{\left( \left[ X \right] R_2^p + R_2^{-(p+1)} \right)}$$

and

$$J_p^{\mu}(\theta) = \frac{J_p^{\mu}(\theta) R_2^p}{\left( \left[ X \right] R_2^p + R_2^{-(p+1)} \right)}$$

The mathematical solution for $B_{p3}$ in terms of known quantities is obtained from equation (A-3e) by substituting the previously obtained expressions for $A_{p3}$ (equation A-6), $A_{p2}$ (equation A-4), and $B_{p2}$ (equation A-8).

$$B_{p3} = \frac{-\frac{1}{\mu_2} J_p^{\mu}(\theta) \left( \left[ X \right] (p+1)R_2^{(p-1)} - (p)R_2^{-p-2} \right) + \frac{1}{\mu_1} J_p^{\mu}(\theta) (p+1)R_2^{(p-1)}}{\left( \frac{1}{\mu_1} R_2^{-p-2} + \frac{1}{\mu_2} \left( \left[ Z \right] [X] (p+1)R_2^{(p-1)} \right) - \frac{1}{\mu_2} \left( \left[ Z \right] R_2^{-p-2} \right) \right)}$$  \hspace{2cm} (A-9a)

where

$$[X] = \frac{-R_1^{-(2p+1)} \left[ 1 + \left( \frac{p}{p+1} \right) \frac{\mu_1}{\mu_2} \right]}{\left( 1 - \frac{\mu_1}{\mu_2} \right)}$$  \hspace{2cm} (A-9b)
\[
[z] = \frac{R_2^{-(p+1)}}{\left(\frac{X}{R_2^p + R_2^{-(p+1)}}\right)} \quad (A-9c)
\]

\[
J''_p(\theta) = \frac{J'_p(\theta) R_2^p}{\left(\frac{X}{R_2^p + R_2^{-(p+1)}}\right)} \quad (A-9d)
\]

\[
J'_p(\theta) = \frac{\mu J_1(\theta)}{l_p(\cos\theta) R_3^{(p-1)(2p+1)}} \quad (A-9e)
\]

After the numerical value for \(B_{p3}\) is calculated on the computer for a specific problem, the numerical values for the other coefficients can be obtained from the following equations:

\[
B_{p2} = B_{p3} [z] + J''_p(\theta), \quad (\text{see equation } A-8) \quad (A-10a)
\]

\[
A_{p3} = J'_p(\theta), \quad (\text{see equation } A-6) \quad (A-10b)
\]

\[
A_{p2} = [X] B_{p2}, \quad (\text{see equation } A-4) \quad (A-10c)
\]

\[
A_{p1} = A_{p2} + B_{p2} R_1^{-(2p+1)}, \quad (\text{see equation } A-5) \quad (A-10d)
\]

\[
B_{p4} = A_{p3} R_3^{(2p+1)} + B_{p3} \quad (\text{see equation } A-7) \quad (A-10e)
\]
APPENDIX B

DETERMINATION OF POTENTIALS FOR INFINITESIMALY THIN CURRENT BAND AND INFINITESIMALY THIN COIL

In this appendix the potentials $A_{\psi I}$ in the inner region and $A_{\psi II}$ in the outer region are derived for the infinitesimally thin current band in a homogeneous medium of permeability $\mu_1$ (see Figure 1-B). Also, the potential in the outer region ($r>R_1$) for the infinitesimally thin coil is shown to reduce to the potential of the circular filamentary current loop.

The potentials in the inner region $A_{\psi I}$ and outer region $A_{\psi II}$ of the infinitesimally thin current band problem are solutions to the vector Laplace's equation $\nabla \times \vec{A} = 0$. These solutions can be expressed as:

$$A_{\psi I} = \sum_{p=1}^{\infty} \left( A_{p1} r^p \right) P_1^*(\cos\theta)$$

$$A_{\psi II} = \sum_{p=1}^{\infty} \left( \frac{B_{p2}}{r(p+1)} \right) P_1^*(\cos\theta)$$

The coefficients $A_{p1}$ and $B_{p2}$ are determined from the boundary conditions of the problem. After algebraic manipulation such as with equations (31) and (35) in the text, the boundary conditions for the normal component of $\vec{B}$ and the tangential component of $\vec{H}$ become:

$$A_{\psi I} = A_{\psi II} \text{ at } r = R_1$$

$$-\frac{1}{\mu_1} \frac{1}{r} \frac{\partial}{\partial r} (rA_{II}) + \frac{1}{\mu_1} \frac{1}{r} \frac{\partial}{\partial r} (rA_{I}) = J_{\psi}(\theta) \text{ at } r = R_1$$

Substituting the expressions for $A_{\psi I}$ and $A_{\psi II}$ (equations B-1a and B-1b) into the boundary value equations (equations B-2a and B-2b) provides us with the following algebraic equations for the coefficients:

$$A_{p1} r^p = B_{p2} r^{-(p+1)}$$

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- \frac{1}{\mu_1} \left[ (-p)B_p^2R_1^{p-2} \right]

+ \frac{1}{\mu_1} \left[ \frac{A_p^1(p+1)R_1^{p-1}}{P_1(cos\theta)} \right] = J_p(\theta) / P_1^1(cos\theta)

where J_p(\theta) is the \( p \)th term of J_\psi(\theta) (see equation 41). These equations are solved for A_p^1 and B_p^2 by simple algebraic manipulation.

\[
A_p^1 = B_p^2R_1^{2p-1}
\]

\[
B_p^2 = \frac{\mu_1 J_p(\theta) / P_1^1(cos\theta)}{R_1^{p-2}(2p+1)}
\]

The potential A_\psi II is determined by substituting the expression for B_p^2 (equation B-4b) into equation (B-4a).

\[
A_\psi II = \sum_{p=1}^{\infty} \left[ \frac{\mu_1 J_p(\theta) / P_1^1(cos\theta)}{r(p+1)(2p+1)R_1^{p-2}} \right] P_1^1(cos\theta)
\]

\[
= \sum_{p=1}^{\infty} \frac{\mu_1 J_p P_1^1(cos\theta)R_1}{(2p+1)} \left( \frac{R_1}{r} \right)^{p+1}
\]

where \( J_p(\theta) = JK_p P_1^1(cos\theta) \) (B-5c)

and

\[
JK_p = \frac{2n+1}{2p(p+1)} \int_0^\pi J(\theta)P_1^1(cos\theta) \sin\theta d\theta
\]

A_\psi II is the potential in region 2 which is external to the coil (see Figure 1-B).
Now the solution for $A_{\psi II}$ (equation B-5b) can be reduced to that for the filamentary coil and the answer compared with that for the same problem from a standard text (Jackson, page 144, equation (5.46)).

The coefficient $J_{k_p}$ for the expansion of the current

$$J_{\psi}(\theta) = \sum_{p} J_{p} P_{p}^{1}(\cos \theta)$$

(B-6)

for the current filament is obtained from the equation (see equation B-5d):

$$J_{k_p} = - \frac{2p+1}{2p(p+1)} \int_{\cos(0)}^{\cos(\pi)} \frac{I}{R_1} \delta(\cos \theta) P_{p}^{1}(\cos \theta) d(\cos \theta)$$

(B-7)

$$= - \frac{I}{R_1} \left( \frac{2p+1}{2p(p+1)} \right) P_{p}^{1}(0)$$
\[ JK_p = \left[ \frac{-(2p+1)}{2p(p+1)} \right] \left[ \frac{I}{R_1} p^1_p(0) \right] \]

where \( J(0) = \frac{I}{R_1} \delta(\cos \theta) \)

The special value of the associated Legendre function is calculated from the expression (where \( m = 1 \))

\[
\begin{align*}
P^m_p(0) &= \left\{ \begin{array}{ll}
(-1)^{(p-m)/2} \frac{(p+m)!}{2^p \left( \frac{p-m}{2} \right) \left( \frac{p+m}{2} \right)!}, & (p+m, \text{ even}) \\
0, & (p+m, \text{ odd})
\end{array} \right. \\
&= 0 \quad \text{,} (p+m, \text{ odd})
\end{align*}
\]

This expression may be derived from the series expansion for the Legendre function (see Smythe) and letting \( \cos \theta = \mu' \) approach 0.

Substituting the expression for \( JK_p \) (equation B-7), into equation (B-5b), results in the expression for the vector potentials \( A_{\psi II} \) in the external region for the filamentary coil.

\[
A_{\psi II} = -\sum_{p=1}^{\infty} \frac{\mu_1 I_p^1(\cos \theta)}{(2p)(p+1)} \left( \frac{R_1}{r} \right)^{p+1} p^1_p(0) \quad \text{(B-9a)}
\]

Now equation (B-9a) must be multiplied by \( \frac{4\pi}{c} \) to change from SI units to Gaussian units, and \( \mu_1 \) must be set equal to 1 as \( \mu_1 \) is the free space permeability which equals 1 in the Gaussian system.

After making these substitutions we have

\[
A_{\psi II} = -\frac{4\pi}{c} \sum_{p=1}^{\infty} \frac{I_p^1(\cos \theta)}{2p(p+1)} \left( \frac{R_1}{r} \right)^{p+1} p^1_p(0) \quad \text{(B-9b)}
\]

Now taking the first term \((p=1)\) for use in the comparison with the result in Jackson we have
This expression agrees exactly with the expression in Jackson\textsuperscript{10} for the first term in the series where $R_1 = a$ in his notation.\textsuperscript{10} The magnetic fields far from the loop for the $p=1$ term are dipole in character.

The $A_{\psi I(p=1)}$ term for the current band problem also reduces exactly to Jackson's term with $n=0$ (Jackson,\textsuperscript{10} page 144, equation 5.46) for the potential inside of the loop.
APPENDIX C
REDUCTION OF THE MAGNETIC VECTOR POTENTIAL
FOR A THIN COIL SURROUNDING A FERROMAGNETIC
SPHERICAL SHELL TO THAT OF A THIN COIL
IN FREE SPACE WHEN IN THE LIMIT \( \mu_1 \)
EQUALS \( \mu_2 \)

In this appendix, the coefficients \( A_{p1}, A_{p2}, A_{p3}, B_{p2}, B_{p3}, \) and \( B_{p4} \)
for the potentials are evaluated for the system consisting of a ferromagnetic shell with permeability \( \mu_2 \) surrounded by an infinitesimally thin current band in a homogeneous medium with permeability \( \mu_1 \) in the limit as \( \mu_1 = \mu_2 \). These coefficients are utilized in equation (28) in the section of the report entitled "Thin Coil Surrounding a Ferromagnetic Spherical Shell". The variables are defined in Figure 2 located in the text of this report. When \( \mu_1 \) is set equal to \( \mu_2 \) the problem reduces to that of finding the potentials in the two regions of a simple current band (see Figure 1-B in Appendix B), since the ferromagnetic shell will now have a permeability \( \mu_1 \) equal to that of the homogeneous medium with permeability \( \mu_1 \).

In this limit the coefficients should assume the following form:

\[
A_{p1} = A_{p2} = A_{p3} = \ldots \tag{C-1a}
\]

\[
B_{p2} = B_{p3} = 0 \tag{C-1b}
\]

and where \( A_{p1} \) and \( B_{p4} \) should reduce to the coefficients for the potentials in the two regions for the spherical band problem (see Appendix B). If the coefficients assume this mathematical form it will prove that the mathematical form of the coefficients for the spherical shell surrounded by a thin current loop are mathematically correct.

The mathematical solution for \( B_{p3} \) in terms of known quantities was derived in Appendix A and was reported in the text of this report (see equation (37a)).

\[
B_{p3} = -\frac{1}{\mu_2} J''(\theta) \left( [X] (p+1)R_2^{-p-1} - (p)R_2^{-p-2} \right) + \frac{1}{\mu_1} J'(\theta) (p+1)R_2^{-p-1} \frac{\left( \frac{1}{\mu_1} (p)R_2^{-p-2} + \frac{1}{\mu_2} [Z][X] (p+1)R_2^{p-1} \right) - \frac{1}{\mu_2} [Z] (p)R_2^{-p-2} \right)}{\left[ \frac{1}{\mu_1} (p)R_2^{-p-2} + \frac{1}{\mu_2} [Z][X] (p+1)R_2^{p-1} \right] \left( \frac{1}{\mu_1} (p)R_2^{-p-2} \right) - \frac{1}{\mu_2} [Z] (p)R_2^{-p-2}} \right] \tag{C-2a}
\]
where

\[
[x] = -\frac{R_1^{-(2p+1)} \left[ 1 + \left( \frac{p}{p+1} \right)^\frac{\mu_1}{\mu_2} \right]}{\left( 1 - \frac{\mu_1}{\mu_2} \right)}.
\]  

(C-2b)

\[
[z] = \frac{R_2^{-(p+1)}}{[x] R_2^p + R_2^{-(p+1)}}.
\]  

(C-2c)

\[
J''''(\theta) = \frac{J_p'(\theta) R_2^p}{[x] R_2^p + R_2^{-(p+1)}}.
\]  

(C-2d)

\[
J''(\theta) = -\frac{\mu_1 J_p(\theta)}{p_1^p(\cos \theta) R_3^{(p-1)(2p+1)}}.
\]  

(C-2e)

The coefficient $B_{p3}$ will now be evaluated when the limit is taken with $\mu_1 = \mu_2$ which cause $[x]$ to approach infinity ($\infty$). Also, the expression for $J''(\theta)$ is substituted into equation (C-2a).
\[ B_{p3} \bigg|_{(\mu_1 = \mu_2)} = \lim_{[X] \to \infty} \left( \frac{\frac{1}{\mu_1} \left( \frac{J_p'(\theta) R_2^p}{R_2 + \frac{R_2}{[X]}} \right)}{\frac{(p+1) R_2^{p-1} - \frac{(p+2)}{[X]}}{\frac{R_2 - (p+1)}{[X]}}} + \frac{1}{\mu_1} \left( \frac{J_p'(\theta)(p+1) R_2^{p-1}}{R_2 + \frac{R_2}{[X]}} \right) \right) \]

\[ \left[ - \frac{1}{\mu_1} \left( \frac{J_p'(\theta)(p+1) R_2^{p-1}}{R_2 + \frac{R_2}{[X]}} \right) + \frac{1}{\mu_1} \left( \frac{J_p'(\theta)(p+1) R_2^{p-1}}{R_2 + \frac{R_2}{[X]}} \right) \right] / \left( \frac{(p+1) R_2^{-(p+1)}}{R_2^p} + \frac{1}{\mu_1} \left( \frac{(p+1) R_2^{-(p+1)}}{R_2^p} \right) \right) \]

\[ B_{p3} \bigg|_{(\mu_1 = \mu_2)} = 0 \]
The expression for \( A_{p2} \) (see equations (38c) and (38a) in the text is:

\[
A_{p2} = [X] B_{p2} = [X] B_{p3} [Z] + [X] J''_p(\theta) \quad (C-4a)
\]

where

\[
B_{p2} = B_{p3} [Z] + J''_p(\theta) \quad (C-4b)
\]

The expression for \( A_{p2} \) when \( \mu_1 \) equals \( \mu_2 \) can be expressed as

\[
A_{p2} \left|_{(\mu_1 = \mu_2)} \right. = \begin{aligned} \lim_{[X] \to \infty} & \left( [X] \begin{bmatrix} B_{p3} & [Z] \end{bmatrix} \right) \\
+ & \lim_{[X] \to \infty} \left( [X] J''_p(\theta) \right) \end{aligned} \quad (C-5)
\]

\[
A_{p2} \left|_{(\mu_1 = \mu_2)} \right. = J'_{p}(\theta)
\]

where

\[
\lim_{[X] \to \infty} \left( [X] [Z] \right) = \lim_{[X] \to \infty} \left( [X] R_2^{-(p+1)} \right) = \lim_{[X] \to \infty} \left( [X] R_2^{p} + R_2^{-(p+1)} \right) = \]

\[
\lim_{[X] \to \infty} \left( [X] \frac{R_2^{-(p+1)}}{R_2^{p} + \frac{R_2^{-(p+1)}}{[X]}} \right) = R_2^{-(2p+1)}
\]

and

\[
\lim_{[X] \to \infty} [X] J''_p(\theta) =
\]

\[
\lim_{[X] \to \infty} \left( [X] J'_{p}(\theta) R_2^{p} \right) = J'_{p}(\theta) \quad (C-6)
\]

and

\[
B_{p3} \left|_{(\mu_1 = \mu_2)} \right. = 0, \text{ (see equation C-3).}
\]
The expression for \( A_{p3} \) equals \( J_1^1(\theta) \) (see equation (38b) in the text of this report). The expression for \( B_{p2} \) (see equation (38a) in text of this report) is:

\[
B_{p2} = B_{p3}[Z] + J_{p}^1(\theta) \tag{C-7}
\]

The expression for \( B_{p2} \) when \( \mu_1 = \mu_2 \) can be expressed as:

\[
B_{p2} = \lim_{[X] \to \infty} \left( \left[ B_{p3} \right]_{\mu_1=\mu_2} \right) [Z] + \lim_{[X] \to \infty} \left( \frac{J_1^1(\theta) R_2^p}{[X] R_2^p + R_2^{-(p+1)}} \right) \tag{C-8}
\]

where

\[
\lim_{[X] \to \infty} [Z] = \lim_{[X] \to \infty} \left( \frac{R_2^{-(p+1)}}{[X] R_2^p + R_2^{-(p+1)}} \right) = 0
\]

and

\[
\lim_{[X] \to \infty} \left( \frac{J_1^1(\theta) R_2^p}{[X] R_2^p + R_2^{-(p+1)}} \right) = 0
\]

and

\[
\lim_{[X] \to \infty} R_{p3} = 0 \quad (\mu_1=\mu_2)
\]

The expression for \( A_{p1} \) is (see equation (38d) in the text)

\[
A_{p1} = A_{p2} + B_{p2} R_{1}^{-(2p+1)} \tag{C-9}
\]
The expression for $A_{p_1}$ when $\mu_1 = \mu_2$ is

$$A_{p_1} = A_{p_2} + \left[ B_{p_2} \right] R_1^{-(2p+1)}$$

$$A_{p_1} = J_p'(\theta)$$

where $B_{p_2} = 0$

The expression for $B_{p_4}$ (see equation (38e) in text) is:

$$B_{p_4} = A_{p_3} R_3^{(2p+1)} + B_{p_3}$$

The expression for $B_{p_4}$ when $\mu_1 = \mu_2$ is

$$B_{p_4} = A_{p_3} R_3^{(2p+1)} + B_{p_3}$$

$$= A_{p_3} R_3^{(2p+1)}$$

where $B_{p_3} = 0$. 

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This means that in the four regions, the potentials used in equation (28) of the report are

\[ A_{\psi I} = \sum_{p=1}^{\infty} \left( A_{p1} r^p \right) p_1^p (\cos \theta) \]  
\[ A_{\psi II} = \sum_{p=1}^{\infty} \left( A_{p2} r^p + \frac{B_{p2}}{r(p+1)} \right) p_1^p (\cos \theta) \]
\[ A_{\psi III} = \sum_{p=1}^{\infty} \left( A_{p3} r^p + \frac{B_{p3}}{r(p+1)} \right) p_1^p (\cos \theta) \]
\[ A_{\psi IV} = \sum_{p=1}^{\infty} \left( \frac{B_{p4}}{r(p+1)} \right) p_1^p (\cos \theta) \]

reduce when \( \mu_1 = \mu_2 \) to the form

\[ A_{\psi I, II, III} = \sum_{p=1}^{\infty} \left( \left[ \begin{array}{c} A_{p1} \\ \mu_1 = \mu_2 \end{array} \right] r^p \right) p_1^p (\cos \theta) \]
\[ A_{\psi IV} = \sum_{p=1}^{\infty} \left( \left[ \begin{array}{c} B_{p4} \\ r(p+1) \end{array} \right] \right) p_1^p (\cos \theta) \]

These are the solutions for the potentials of the current band in a region of space with homogeneous permeability \( \mu_1 \) (see equations (B-1a and B-1b). We now have the solutions for the two potentials in regions I and II \( A_{\psi I, II, III} \) and \( A_{\psi IV} \) respectively) for the simple current band problem. This indicates that the form of the coefficients \( A_{p1} \) and \( B_{p1} \) are mathematically correct.
The mathematical expressions for $A_{p1}$ and $B_{p4}$ will be evaluated in the limit as $\mu_1 = \mu_2$. These values will then be compared with the coefficients $A_{p1}$ and $B_{p2}$, respectively, for the two regions of the current band problem (see Appendix B). $B_{p4}$ (see equation (38e) in text) is:

$$B_{p4} = A_{p3} R_3 (2p+1) + B_{p3}$$

(C-15)

When $\mu_1 = \mu_2$, $B_{p4}$ is:

$$B_{p4} = \left[\begin{array}{c} A_{p3} \\ R_3 (2p+1) + B_{p3} \end{array}\right]_{\left(\mu_1=\mu_2\right)}$$

where

$$A_{p3} = J_p(\theta)$$

$$B_{p3} = 0$$

and

$$B_{p4} = \left[\begin{array}{c} \mu_1 J_p(\theta) \\ P_{p}^1(\cos \theta) R_3^{-p-2} (2p+1) \end{array}\right]_{\left(\mu_1=\mu_2\right)}$$

(C-16)

The form of $A_{p1}$ is:

$$A_{p1} = \left[\begin{array}{c} B_{p4} \\ R_3^{-2p-1} \end{array}\right]_{\left(\mu_1=\mu_2\right)}$$

(C-17)
The mathematical expressions for $A_{p1}$ and $B_{p4}$ (equations C-17 and C-16, respectively) for the ferromagnetic spherical shell surrounded by a thin current band in the limit as $\mu_1 = \mu_2$ are the same as the coefficients $A_{p1}$ and $B_{p2}$ (see equations B-4a and B-4b), respectively, for the vector potentials in the regions of the current band in free space (see Appendix B). It is noted that when making the comparison $R_3$ must be set equal to $R_1$. For comparison, the coefficients for the current band problem are:

$$A_{p1} = B_{p4} R_{p4}^{-2p-1} \quad \text{(C-18a)}$$

$$B_{p2} = \frac{\mu_1 J_p(\theta)}{p^1_p(\cos \theta) R_{p1}^{p-2}(2p+1)} \quad \text{(C-18b)}$$

and the coefficients for the ferromagnetic shell problem with $\mu_1 = \mu_2$ are:

$$A_{p1} = B_{p4} R_{p4}^{-2p-1} \quad \text{(C-19a)}$$

$$B_{p4} = \frac{\mu_1 J_p(\theta)}{p^1_p(\cos \theta) R_{p4}^{p-2}(2p+1)} \quad \text{(C-19b)}$$
APPENDIX D

SOLUTION OF THE AZIMUTHAL COMPONENT OF THE VECTOR
POISSON’S EQUATION $\mathbf{\nabla} A_\psi = -\mu J_\psi$ IN
SPHERICAL COORDINATES

For the benefit of the reader, the azimuthal component ($\psi$ component) of the vector Poisson's equation in spherical coordinates as originally derived by Purczyński is presented in detail as related to the problems addressed in this report. Because of the spherical symmetry of this problem, only the $\psi$ component of the vector Poisson's equations is needed. Following in an outline of Purczyński’s development, the general form of the component of the current is:

$$J_\psi(r,\theta) = J r^{q-2} \sum_{p=1}^{\infty} K_p P_1^p(\cos\theta)$$  \hspace{1cm} (D-1)

where the case $q = 2$ is of primary concern in this work. The general $\psi$ component of Poisson's equation is written as

$$\mathbf{\nabla} A_\psi = \frac{\partial^2 A_\psi}{\partial r^2} + \frac{1}{r} \frac{\partial A_\psi}{\partial r} - \frac{A_\psi}{r^2 \sin^2 \theta} + \frac{1}{r^2} \frac{\partial^2 A_\psi}{\partial \theta^2} + \cot \theta \frac{\partial A_\psi}{\partial \theta} =$$

$$\begin{cases} -\mu J_\psi(r,\theta) & \text{in current region} \\ 0 & \text{otherwise} \end{cases}$$  \hspace{1cm} (D-2)

Multiplying $\mathbf{\nabla} A_\psi$ by $r^2$ and substituting the general expression for $J_\psi(r,\theta)$ in equation (D-1) gives the expression

$$r^2 \frac{\partial^2 A_\psi}{\partial r^2} + 2r \frac{\partial A_\psi}{\partial r} - \frac{A_\psi}{\sin^2 \theta} + \frac{\partial^2 A_\psi}{\partial \theta^2} + \cot \theta \frac{\partial A_\psi}{\partial \theta} =$$

$$= - \mu J r^q \sum_{p=1}^{\infty} K_p P_1^p(\cos\theta)$$  \hspace{1cm} (D-3)

which is assumed to have a solution of the form

\[ \text{51} \]
\[ A = A = \sum_{p=1}^{\infty} f(r) P^1_p(\cos \theta) \]  

(D-4)

By separation of variables, equation (D-3) becomes:

\[
\frac{d^2}{d\theta^2} \left[ P^1_p(\cos \theta) \right] + \frac{d}{d\theta} \left[ P^1_p(\cos \theta) \right] \cot \theta + \frac{p(p+1)}{\sin^2 \theta} P^1_p(\cos \theta) = 0
\]  

(D-5a)

\[
r^2 \frac{d^2 f}{dr^2} + 2r \frac{df}{dr} - p(p+1)f = - \nu_2 J_r q_k^p
\]  

(D-5b)

where the separation constant \( p(p+1) \) is an integer. Differential equations of the form

\[
\frac{d^2 y}{dx^2} + p(x) \frac{dy}{dx} + Q(x)y = R(x)
\]  

(D-6)

have no general solution. The homogeneous part of equation (D-5b) has the form

\[
r^2 \frac{d^2 f}{dr^2} + 2r \frac{df}{dr} - p(p+1)f = 0
\]  

(D-7)

Equation (D-7) can be simplified by substituting \( r = e^t \). Making the following substitutions in equation (D-7),

\[
\frac{df}{dr} = \frac{df}{dt} \frac{dt}{dr} = \frac{df}{dt} \left( \frac{1}{r} \right)
\]  

(D-8)

\[
\frac{d^2 f}{dr^2} = \frac{d^2 f}{dt^2} \left( \frac{dt}{dr} \right)^2 + \frac{df}{dt} \frac{d^2 t}{dr^2}
\]
\[
\frac{d^2f}{dr^2} = \frac{d^2f}{dt^2} \left(\frac{1}{r^2}\right) + \frac{df}{dt} \left(-\frac{1}{r^2}\right)
\]

where \(\frac{dt}{dr} = \frac{1}{r}\), \(\frac{d^2t}{dr^2} = -\frac{1}{r^2}\), \(\text{Note: } \Delta n(r) = t\)

yields

\[
\frac{d^2f}{dt^2} + \frac{df}{dt} - p(p+1)f = 0 \quad (D-9)
\]

This has the well-known mathematical solution:

\[
f_1 = A_p e^{bt} + B_p e^{-(p+1)t} \quad (D-10)
\]

which after substitution of \(r = e^t\) has the form

\[
f_1 = A_p r^p + \frac{B_p}{r^{(p+1)}} \quad (D-11)
\]

Thus the general mathematical solution to the homogeneous part of the
azimuthal component of Poisson's equation is

\[
A' = A'_\psi = \sum_{p=1}^{\infty} \left(A_p r^p + \frac{B_p}{r^{(p+1)}}\right) p_p^1(\cos0) \quad (D-12)
\]

which is the solution to the azimuthal component of the vector Laplace's
equation.

The solution to the inhomogeneous equation \((D-5b)\) will now be investi-
gated. It is assumed that the mathematical solution to equation \((D-5b)\)
has the general form

\[
f_2 = d e^{qt} \quad (D-13)
\]

for \(p \neq q\). By algebraic manipulation after substituting into equation
\((D-5b)\) we have:

53
\[ d_p = \frac{\mu_2 J K_p}{(p-q)(p+q+1)} \text{, (} p \neq q \text{)} \quad (D-14) \]

If we assume that the mathematical solution to equation (D-5b) has the general form for \( p = q \)

\[ f'_2 = d q e^{qt} \quad (D-15) \]

It is found after substituting \( f'_2 \) into equation (D-5b) that

\[ d = -\frac{\mu_2 J K_q}{2q+1} \text{, (} p=q \text{)} \quad (D-16) \]

Since \( A \) equals \( \sum_{p=1}^{\infty} f(r) P_1^q(\cos \theta) \), the general mathematical solution to the inhomogeneous equation (D-5b) has the form

\[ A'' = A'' = \mu_2 J r^q \left[ \sum_{p=1}^{\infty} \frac{K_p^1(\cos \theta)}{(p-q)(p+q+1)} - \frac{K_q^1(\cos \theta) \ln(r)}{2q+1} \right] \quad (D-17) \]

The total general solution to equation (D-2) consists of the sum of the homogeneous and inhomogeneous equation.

\[ A = A' + A'' = A_p + A_p'' = \sum_{p=1}^{\infty} \left[ A_p r^p + \frac{3}{r(r+1)} \right] P^p_1(\cos \theta) \]

\[ + \mu_2 J r^q \left[ \sum_{p=1}^{\infty} \frac{K_p^1(\cos \theta)}{(p-q)(p+q+1)} - \frac{K_q^1(\cos \theta) \ln(r)}{2q+1} \right] \quad (D-18) \]

For the problem worked in this report \( q = 2 \) and \( K_p = 0 \) for even \( p \). Thus, \( K_2 \) is 0 and the term involving

\[ -\mu_2 J r^2 \left[ \frac{K_2^1 P(r) \ln(r)}{5} \right] \]
in equation (D-18) does not contribute. In this case (D-18) reduces to (see equation (53c) in text of report where $A_p = A_{p3}$ and $B_p = B_{p3}$).

\[ A_{III} = A_{\psi III} = \sum_{p=1}^{\infty} \left[ A_p \frac{B_p}{r^{p+1}} \right] p^1_p (\cos \theta) \]

\[ + \mu_2 Jr^2 \sum_{p=2}^{\infty} \frac{K_p p^1_p (\cos \theta)}{(p-2)(p+3)} \]  

(D-19)
APPENDIX E

CALCULATION OF COEFFICIENTS OF THE VECTOR POTENTIAL FOR A SOLID FERROMAGNETIC SPHERE SURROUNDED BY A COIL OF FINITE WIDTH

In this appendix we derive the coefficients for the magnetic vector potentials in regions I—IV for a solid ferromagnetic sphere surrounded by a finite width current band. For a detailed discussion of the ferromagnetic problem see the section in the text of the report entitled "Ferromagnetic Sphere Surrounded by Coil of Finite Width". The vector potentials in each region are:

\[ A_I = A_{\psi_I} = \sum_{p=1}^{\infty} (A_{p1} r^p) p_1^1 (\cos \theta) \]  
\[ A_{II} = A_{\psi_{II}} = \sum_{p=1}^{\infty} \left( A_{p2} r^p + \frac{B_{p2}}{r^{p+1}} \right) p_1^1 (\cos \theta) \]  
\[ A_{III} = A_{\psi_{III}} = \sum_{p=1}^{\infty} \left( A_{p3} r^p + \frac{B_{p3}}{r^{p+1}} \right) p_1^1 (\cos \theta) \]  

\[ + \sum_{p'=2, p \neq 2}^{\infty} \left( \frac{\mu_2 J K p^2}{r^{p-2}(p+3)} \right) p_1^1 (\cos \theta) \]  
\[ A_{IV} = A_{\psi_{IV}} = \sum_{p=1}^{\infty} \left( \frac{B_{p4}}{r^{p+1}} \right) p_1^1 (\cos \theta) \]

The coefficients \( A_{p1} \) and \( B_{p4} \) in equations (E-1a to E-1d) are obtained by substituting these equations into the boundary conditions (equations E-2a to E-2f).

\[ A_I = A_{II} \text{ at } r = R_1 \]  
\[ A_{II} = A_{III} \text{ at } r = R_2 \]
After appropriate substitutions of equations (E-1a to E-ld) into equations (E-2a to E-2f) the following boundary value equations are obtained.

\[ A_{III} = A_{IV} \text{ at } r = R_3 \]  
(E-2c)

\[ \frac{1}{\mu_2} \frac{1}{r} \frac{\partial}{\partial r} (rA_{II}) = \frac{1}{\mu_1} \frac{1}{r} \frac{\partial}{\partial r} (rA_I) \text{ at } r = R_1 \]  
(E-2d)

\[ \frac{1}{\mu_2} \frac{1}{r} \frac{\partial}{\partial r} (rA_{III}) = \frac{1}{\mu_2} \frac{1}{r} \frac{\partial}{\partial r} (rA_{II}) \text{ at } r = R_2 \]  
(E-2e)

\[ \frac{1}{\mu_2} \frac{1}{r} \frac{\partial}{\partial r} (rA_{IV}) = \frac{1}{\mu_2} \frac{1}{r} \frac{\partial}{\partial r} (rA_{III}) \text{ at } r = R_3 \]  
(E-2f)

\[ A_{p1R_1} = A_{p2R_1} + \frac{B_{p2}}{R_1^{p+1}} \]  
(E-3a)

\[ A_{p2R_2} + B_{p2R_2}^{-(p+1)} = A_{p3R_2} + B_{p3R_2}^{-(p+1)} + \left( \frac{\mu_2 J_{R_2}}{p_2} \right)^{2} \frac{K}{(p-2)(p+3)} \]  
(E-3b)

\[ A_{p3R_3} + B_{p3R_3}^{-(p+1)} + \frac{\mu_2 J_{R_3}}{p_3} \frac{K}{(p-2)(p+3)} = B_{p4R_3}^{-(p+1)} \]  
(E-3c)

\[ \frac{1}{\mu_2} \left[ A_{p2(p+1)R_1}^{(p-1)} - (p)B_{p2R_1}^{-(p+2)} \right] = \frac{1}{\mu_1} A_{p1(p+1)R_1}^{(p-1)} \]  
(E-3d)
These algebraic equations provide six simultaneous equations with six unknowns, and can be solved for the coefficients \((A_1\) and \(B_1\)) by algebraic manipulation.

Solving algebraically equations (E-3a) and (E-3d) results in the following solution for \(A_2\) in terms of \(B_2\):

\[
A_2 = [x] B_2
\]  

(E-4)

where \([x] = -R_1^{-(2p+1)} \left[ 1 + \left( \frac{\tau}{p+1} \right) \frac{\mu_1}{\mu_2} \right] \left( 1 - \frac{\mu_1}{\mu_2} \right)\)

The solution for \(A_1\) from equation (E-3e) is:

\[
A_1 = A_2 + B_2 R_1^{-(2p+1)}
\]  

(E-5)

Also, solving equation (E-3c) and (E-3f) algebraically for mathematical expressions describing \(B_4\) gives the expression for \(A_3\) in terms of \(B_3\) and known quantities after equating the functions for \(B_4 = B_4\) from each equation.
\[ A_{p3} = K_p' \]  \hfill (E-6)

\[ K_p' = - \frac{\mu_{2JK} R_3^{-(p+2)}}{(p-2)(2p+1)} \]

The algebraic solution of \( B_{p4} \) from equation (E-3c) is:

\[ B_{p4} = A_{p3} R_3^{(2p+1)} + B_{p3} + \frac{\mu_{2JR} R_3^{(p+3)} K_p}{(p-2)(p+3)} \]  \hfill (E-7)

The following expression is obtained for \( B_{p2} \) from equation (E-3b) after substituting the expressions for \( A_{p3} \) (equation E-6) and \( A_{p2} \) (equation E-4).

\[ B_{p2} = B_{p3} [Z] + K_p'' \]  \hfill (E-8)

where \([Z] = \frac{R_2^{-(p+1)}}{([X] R_2^p + R_2^{-(p+1)})}\)

\[ K_p'' = \frac{K_p' R_2^p + \frac{\mu_{2JR} R_2^2 K_p}{(p-2)(p+3)}}{([X] R_2^p + R_2^{-(p+1)})} \]

The mathematical solution for \( B_{p3} \) in terms of known quantities is obtained from equation (E-3e), by substituting the previously obtained expressions for \( A_{p3} \) (equation E-6), \( A_{p2} \) (equation E-4), and \( B_{p2} \) (equation E-8).
\[ B_{p3} = \left\{ -K'_p \left[ (p+1)R_2^{(p-1)} \right] - \frac{3\mu_2^2 JR_2^2 K}{(p-2)(p+3)} \right. \]
\[ + \left[ X \right] (p+1)R_2^{(p-1)}K'_p - (p)R_2^{-(p+2)}K''_p \}
\]
\[ \{ (-p)R_2^{-(p+2)} - [Z] [X] (p+1)R_2^{-p-1} + (p)R_2^{-(p+2)} [Z] \}
\]

where
\[ [X] = \frac{-R_1^{-(2p+1)} \left[ 1 + \left( \frac{p}{p+1} \right) \frac{\mu_1}{\mu_2} \right]}{\left( 1 - \frac{\mu_1}{\mu_2} \right)} \] (E-9b)

\[ K'_p = -\frac{\mu_2^2 JR_2^2 K}{(p-2)(2p+1)} \] (E-9c)

\[ [Z] = \frac{R_2^{-(p+1)}}{\left( [X] R_2^p + R_2^{-(p+1)} \right)} \] (E-9d)

\[ K''_p = \frac{\mu_2^2 JR_2^2 K}{(p-2)(p+3)} + \frac{K'_p R_2^p}{\left( [X] R_2^p + R_2^{-(p+1)} \right)} \] (E-9e)

After a numerical value for \( B_{p3} \) is calculated on the computer for a specific problem, the numerical values for the other coefficients can be obtained from the following equations.

\[ B_{p2} = B_{p3} [Z] + K''_p, \text{ (see equation E-8) } \] (E-10a)
\[ A_{p3} = K_p \] (see equation E-6) \hfill (E-10b)

\[ A_{p2} = \begin{bmatrix} x \end{bmatrix} B_{p2} \] (see equation E-4) \hfill (E-10c)

\[ A_{p1} = A_{p2} + B_{p2} R_1^{-2(p+1)} \] (see equation E-5) \hfill (E-10d)

\[ B_{p4} = A_{p3} R_3^{2(p+1)} + B_{p3} + \frac{\mu_{2JR} R_3^{p+3} K_p}{(p-2)(p+3)} \] (see equation E-7) \hfill (E-10e)
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Subj: Rept DTNSRDC/PAS-78-35 of March 1979 entitled "The Magnetic Induction of the System Consisting of a Coil and a Ferromagnetic Spherical Body", changes to

Encl: (1) Changes to DTNSRDC/PAS-78-35

1. Enclosure (1) is forwarded herewith as replacements for pages 19, 37, 38, and 39 of subject report.

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The identity
\[ \int_0^\pi p_{p'}^m(\cos \theta) p^m_p(\cos \theta) \sin \theta d\theta = \frac{2(p+m)!}{(2p+1)(p-m)!} \delta_{p',p} \] 
was used to determine \( K_p \) (equation 42). Setting \( J_\psi (\theta) \) to a constant \( J \) we can express equation (42) as:
\[ K_p = \frac{2p+1}{2p(p+1)} \int_0^\pi p^1_p(\cos \theta) \sin \theta d\theta \] 
(44)

Since the current in this problem extends from \( \left( \frac{\pi}{2} - \alpha \right) \) to \( \left( \frac{\pi}{2} + \alpha \right) \), see Figure 4, the expression for \( K_p \) (equation 44) may be written as
\[ K_p = \frac{2p+1}{2p(p+1)} \left[ \int_{\frac{\pi}{2} - \alpha}^{\frac{\pi}{2}} p^1_p(\cos \theta) \sin \theta d\theta + \int_{\frac{\pi}{2}}^{\frac{\pi}{2} + \alpha} p^1_p(\cos \theta) \sin \theta d\theta \right] \]
(45)

By noting that
\[ p^1_p(-\cos \theta) = (-1)^p p^1_p(\cos \theta) \]
(46)

it follows that the associated Legendre functions \( p^1_p(\cos \theta) \) are even functions with respect to \( \cos \theta \) when \( p \) is odd. The expression for \( K_p \) may be simplified to
\[ K_p = \frac{2p+1}{p(p+1)} \int_{\frac{\pi}{2} - \alpha}^{\frac{\pi}{2}} p^1_p(\cos \theta) \sin \theta d\theta \]
(47)

when \( p \) is odd (\( K_p = 0 \) when \( p \) is even) after utilizing the symmetry of \( J(\theta) \) in Figure 5. By changing the variable in equation (47) to \( \theta' = \cos \theta \), the integral for \( K_p \) may be written as
\[ K_p = \frac{2p+1}{p(p+1)} \int_0^{\sin \alpha} p^1_p(\theta') d\theta' \]
(48)
Now the solution for $A_{\psi I I}$ (equation B-5b) can be reduced to that for the filamentary coil and the answer compared with that for the same problem from a standard text (Jackson, page 144, equation (5.46)).

The coefficient $J_K$ for the expansion of the current

$$J_\psi(\theta) = \sum_p J_K P_p^1(\cos \theta)$$

(B-6)

for the current filament is obtained from the equation (see equation B-5d):

$$J_K = - \frac{2p+1}{2p(p+1)} \int_{\cos(0)}^{\cos(\pi)} \frac{I}{R_1} \delta(\cos \theta) P_p^1(\cos \theta) d(\cos \theta)$$

(B-7)

$$= \frac{I}{R_1} \left( \frac{2p+1}{2p(p+1)} \right) P_p^1(0)$$
\[ J_k = \left[ \frac{(2p+1)}{2p(p+1)} \right] \left[ \frac{I}{R_1} P_k^p(0) \right] \]

where \( J(\theta) = \frac{I}{R_1} \delta(\cos \theta) \)

The special value of the associated Legendre function is calculated from the expression (where \( m = 1 \))

\[
P^m_p(0) = \begin{cases} (-1)^{(p-m)/2} \frac{(p+m)!}{(2p)! \left( \frac{p-m}{2} \right)! \left( \frac{p+m}{2} \right)!}, & (p+m, \text{ even}) \\ 0, & (p+m, \text{ odd}) \end{cases} \quad (B-8)
\]

This expression may be derived from the series expansion for the Legendre function (see Smythe) and letting \( \cos \theta = \mu \) approach 0.

Substituting the expression for \( P^m_p \) (equation B-7), into equation (B-5b) results in the expression for the vector potentials \( A_{\Psi II} \) in the external region for the filamentary coil.

\[
A_{\Psi II} = \sum_{p=1}^{\infty} \frac{\mu_1 I P_k^p(\cos \theta)}{(2p)(p+1)} \left( \frac{R}{r} \right)^{p+1} P_k^p(0) \quad (B-9a)
\]

Now equation (B-9a) must be multiplied by \( \frac{4\pi}{c} \) to change from SI units to Gaussian units, and \( \mu_1 \) must be set equal to 1 as \( \mu_1 \) is the free space permeability which equals 1 in the Gaussian system.

After making these substitutions we have

\[
A_{\Psi II} = \frac{4\pi}{c} \sum_{p=1}^{\infty} \frac{I P_k^p(\cos \theta)}{2p(p+1)} \left( \frac{R}{r} \right)^{p+1} P_k^p(0) \quad (B-9b)
\]

Now taking the first term (\( p=1 \)) for use in the comparison with the result in Jackson, we have
Equation (B-9c) agrees exactly with the first term in the series by Jackson,\textsuperscript{10} where \( R_{\perp} = a \) in his notation, except for a minus sign. When the \((-1)\) phase factor in the definition of the Associated Legendre functions \( P_{\ell}^{m}(\cos \theta) \) is taken into account, the two expressions are the same. The general expressions for the Associated Legendre functions \( P_{\ell}^{m}(\cos \theta) \) in this work do not contain the \((-1)^{m}\) phase factor used by Jackson.

The \( A_{\psi_{\ell}^{I}(p=1)} \) term for the current band problem also reduces exactly to Jackson's term for \( n=0 \) (Jackson,\textsuperscript{10} page 144, equation 5.46) for the potential inside the loop when the \((-1)\) phase factor is again taken into account.